

BEYOND VISION

BLIND ASSISTANCE TOOL



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Demo

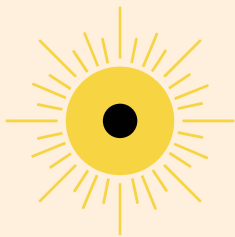
04

HW & SW Specs

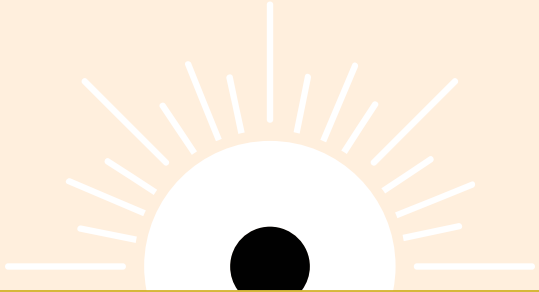
05

Other Considerations





MOTIVATION



MOTIVATION

ACCESSIBILITY

Navigating curbs, stairs, ledges could be a challenge



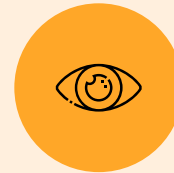
COSTLY

Training both guide dogs and users can cost up to \$50000 [1]



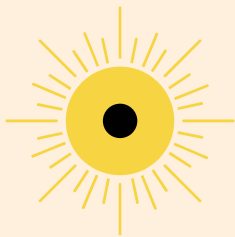
SAFETY

Smoke detectors are not mandatory in households prior to 2018 [2]

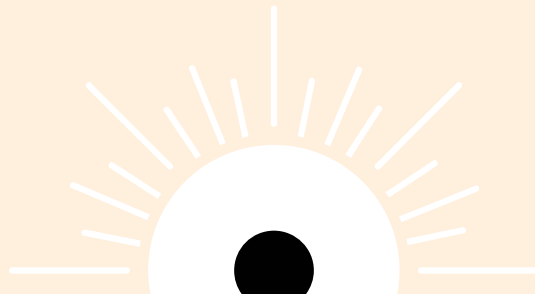


[1] Guide Dogs Singapore, "Guide Dog Programme," [Online]. Available: <https://guidedogs.org.sg/guide-dogs/guide-dog-programme/>

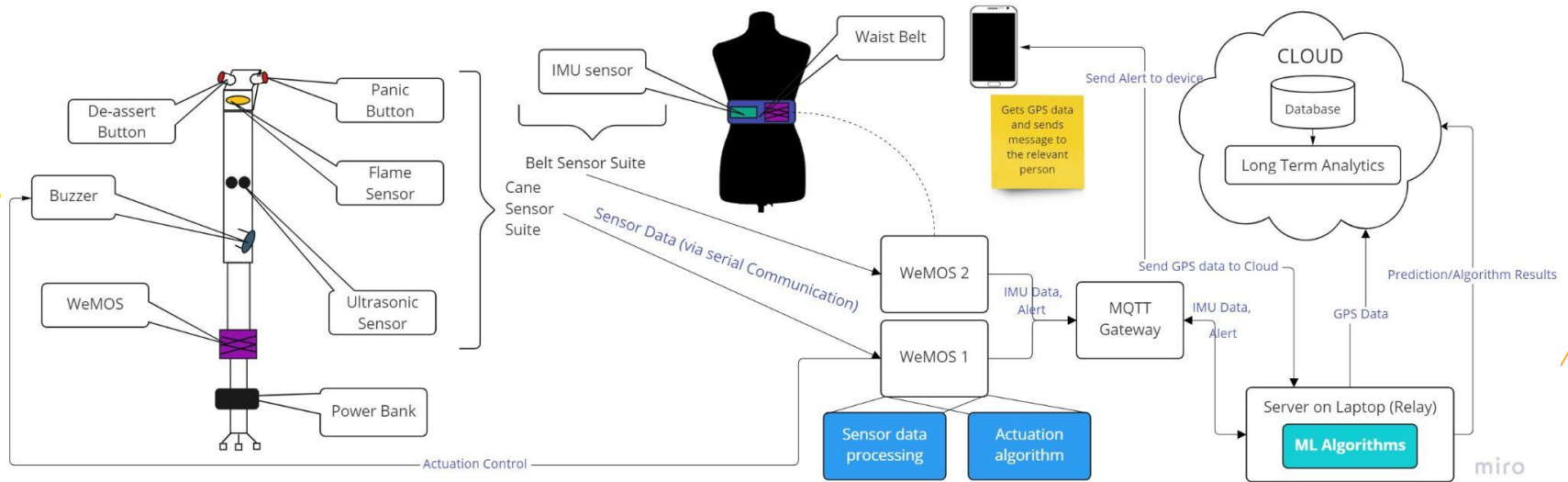
[2] N. J. Sen, "Smoke detectors mandatory in all new homes from June 2018; existing home owners also urged to comply," *The Straits Times*, 16 November 2017.

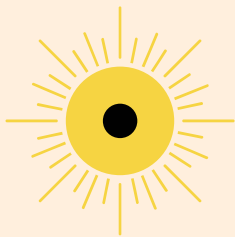


SYSTEM ARCHITECTURE

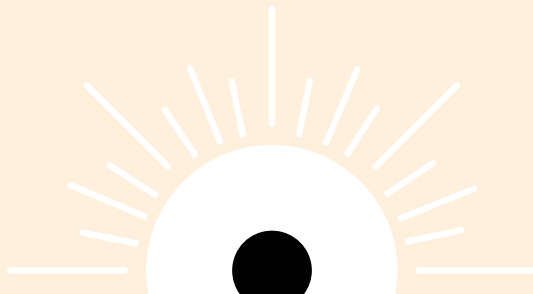


SYSTEM ARCHITECTURE





DEMO



DEMO



01



Smart Walking Cane

Panic Button → Fast Beep →
Telegram Message
Flame Sensor → Slow Beep → Telegram
Message
Proximity sensor → Normal Beep

02



Waist Belt

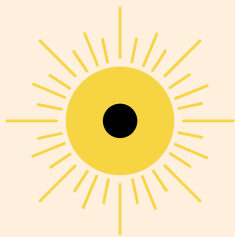
Idle, Walking, Sitting / Getting
Up
Fall → Telegram Message

03

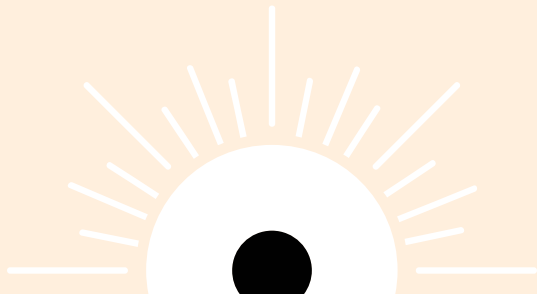


Long Term Analytics

Front-End Showcase



TECHNICAL DETAILS



HARDWARE: WALKING CANE

Flame Sensor [1]

Operating Current: 15 mA
Voltage: 5V
Power: 0.075W



Ultrasonic Sensor [2]

Operating Current: 15 mA
Voltage: 5V
Power: 0.075W

Buzzer [3]

Operating Current: 30 mA
Voltage: 5V
Power: 0.150W

Life-Time

10000 mAh / 60mA = 166 h = 1 Week



[1] <https://www.sunrom.com/p/fire-flame-sensor-module>

[2] <https://cdn.sparkfun.com/datasheets/Sensors/Proximity/HCSR04.pdf>

[3] <https://www.farnell.com/datasheets/2171929.pdf>

HARDWARE: WAIST BELT



MPU-6500 [1]

Operating Current (gyroscope): 3.2 mA

Operating Current (accelerometer): 0.45 mA

Voltage: 3.4V

Power: 0.01241W

Life-time: 1150 mAh [2] / 3.65 mA = 315h = 2 weeks*

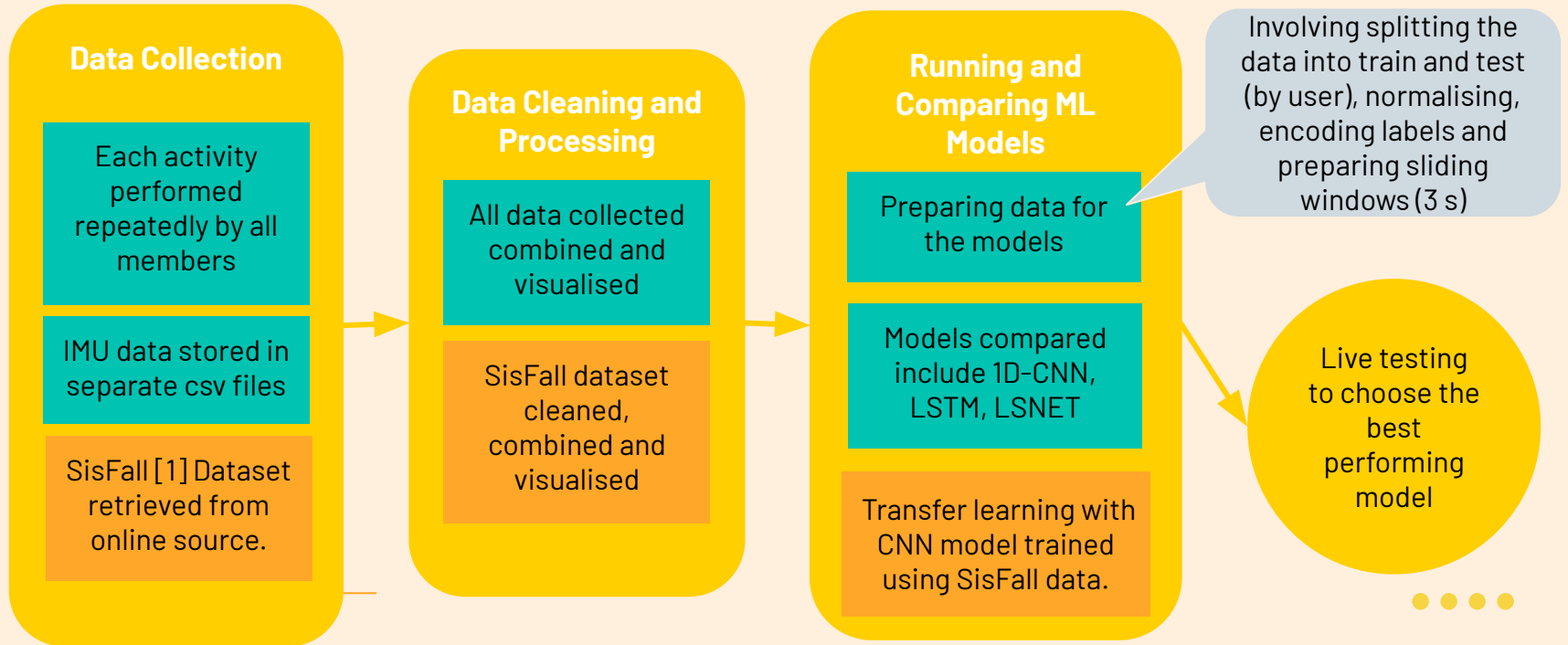


* Theoretical life-time before recharge - however, on low power delivery the IMU data becomes inaccurate

[1] <https://invensense.tdk.com/download-pdf/mpu-6500-datasheet/>

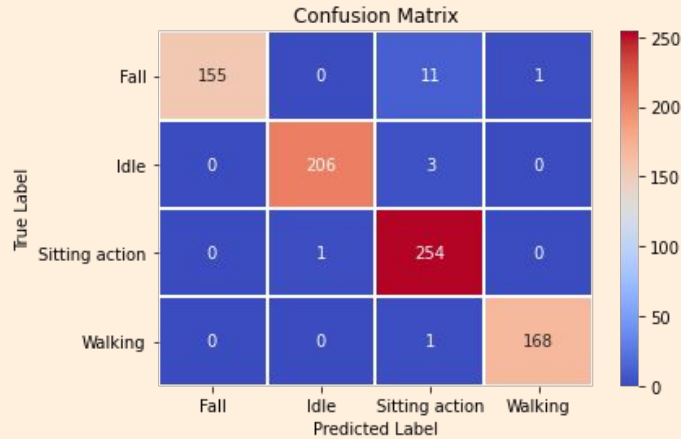
[2] https://www.redcheetah.com/reidsvilleoffice/outpost/item_details/EVEE91BP4

ML MODEL: THE PROCESS

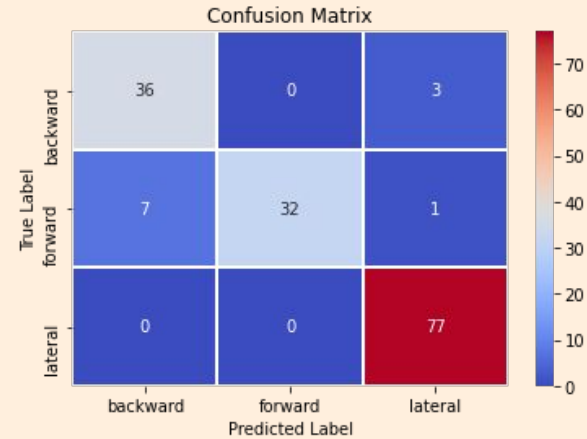


ML MODEL: TRAINING RESULTS

- The system is supported by ML models for the following:
 - *Active activity monitoring for fall detection*
 - *Detecting fall types for use in long term analytics*



Best Model CNN for activity detection



Best Model CNN for fall types



Confusion matrices testing with data collected from one of the team members (not used in training) of the best chosen models

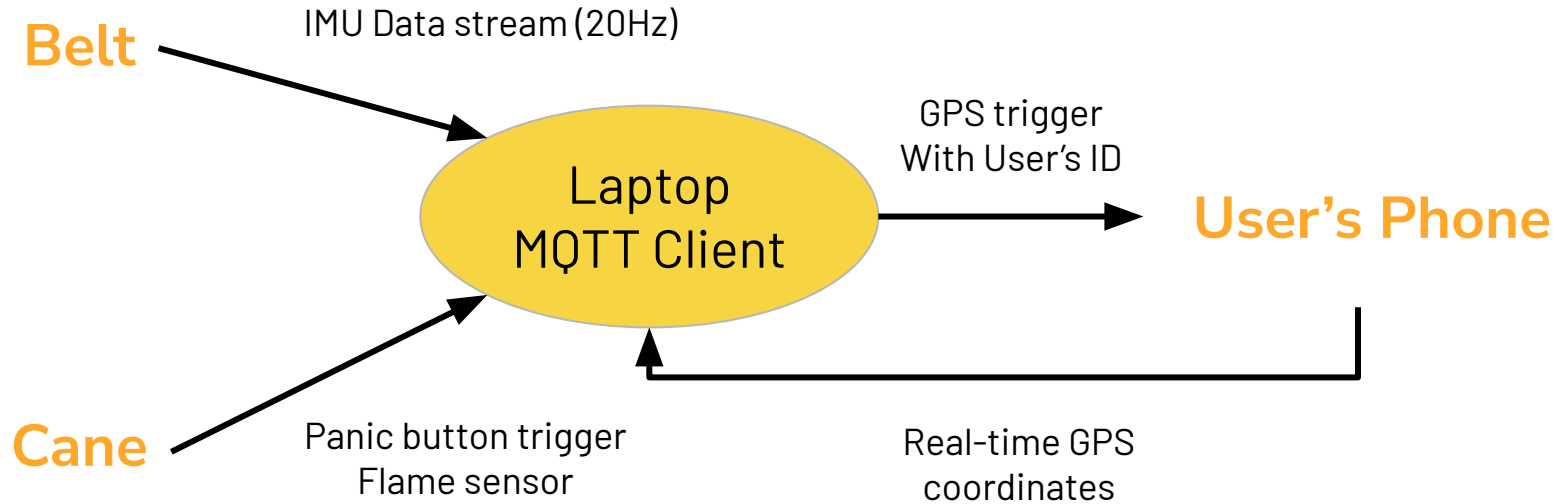
ML MODEL: MODEL TESTING

The activity detection system worked well with both CNN and Transfer learning. However, CNN showed better results while live testing and was also faster in terms of response time and hence was our final chosen model

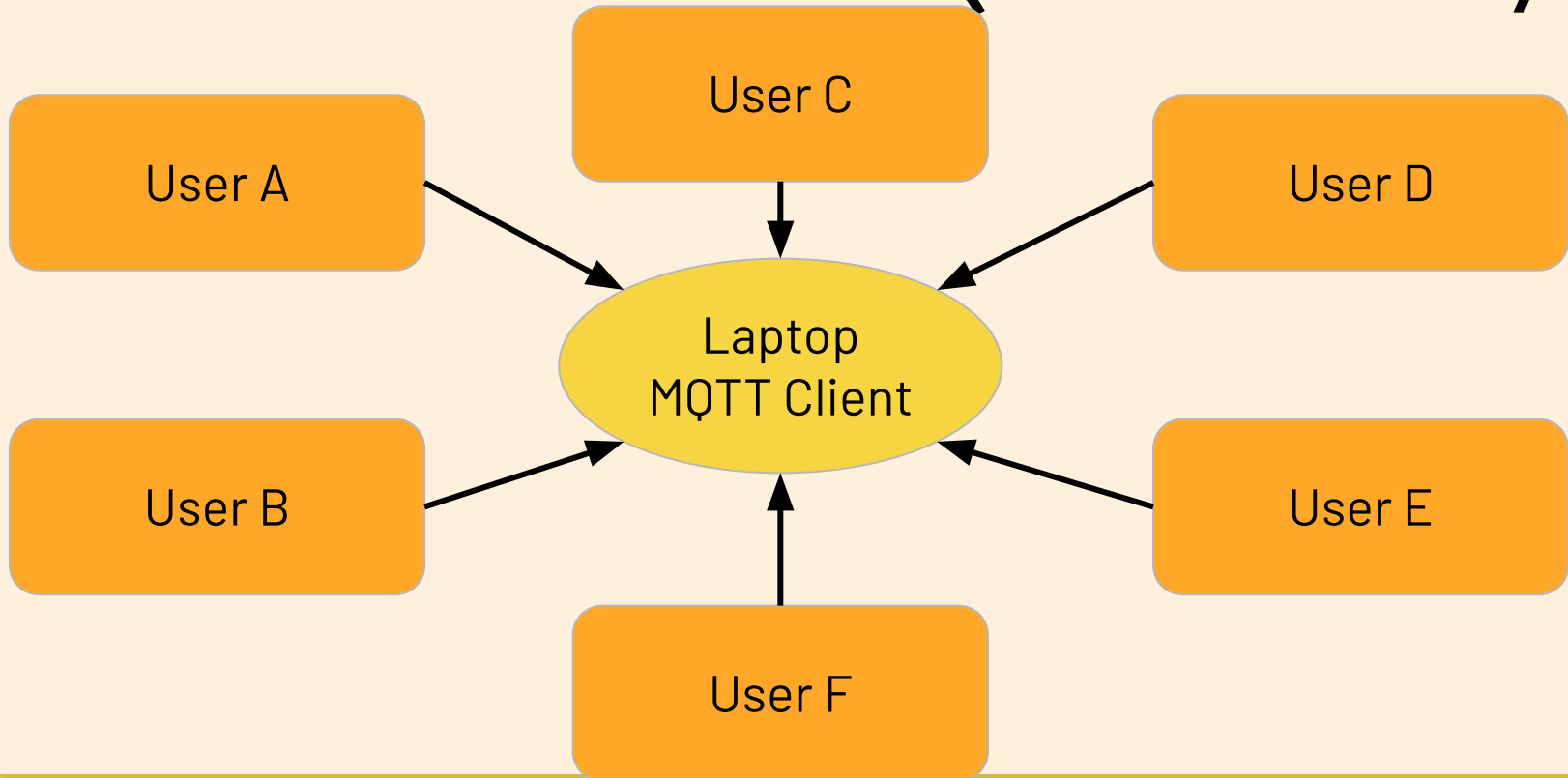


The best performing model for fall types detection was CNN.

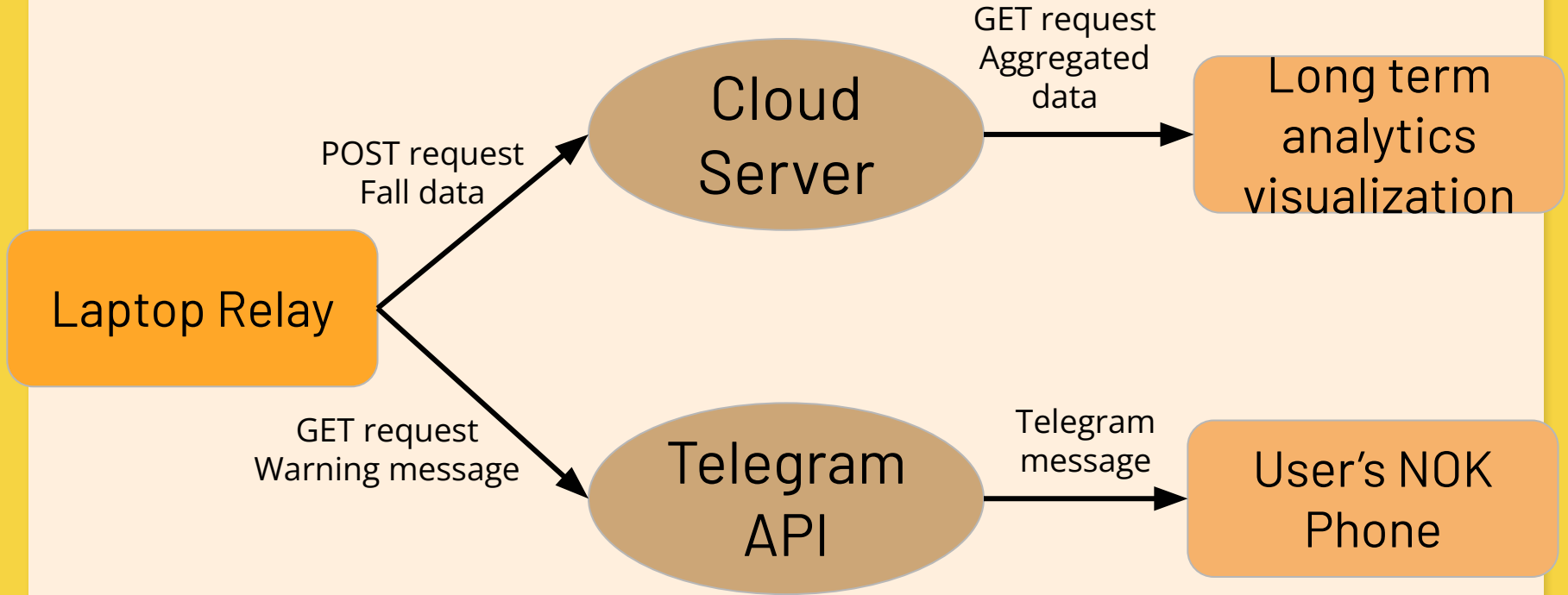
Communications - MQTT



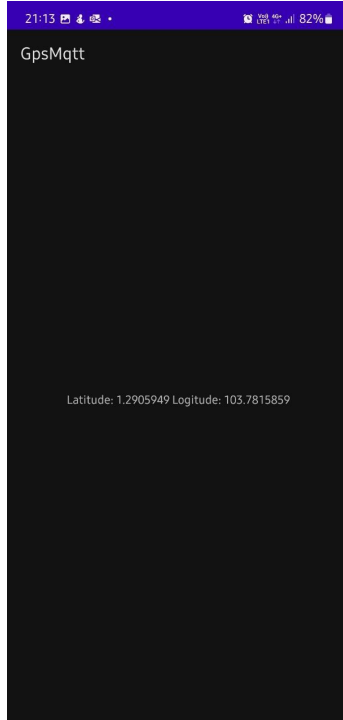
Communications - MQTT- Scalability



Communications - RESTful API



ANDROID GPS & GOOGLE MAPS INTEGRATION



Fall detected at

<https://www.google.com/maps/place/1.2907655,103.7814883>

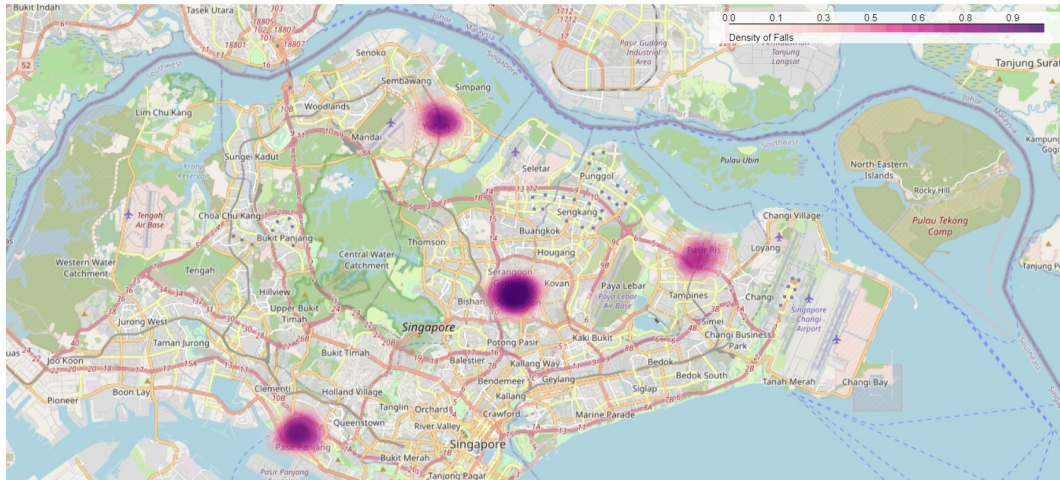
2:58 PM

CLOUD

Target user: Urban planners

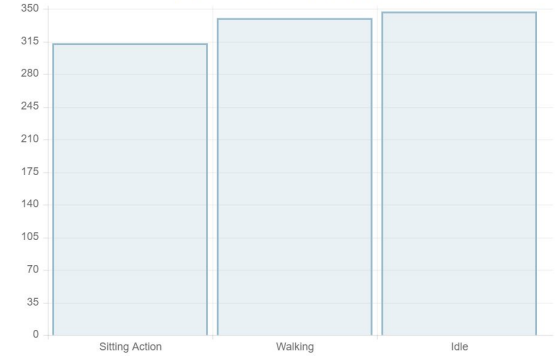
1. Where
2. Why

Heatmap of Aggregated Falls per Unit Area



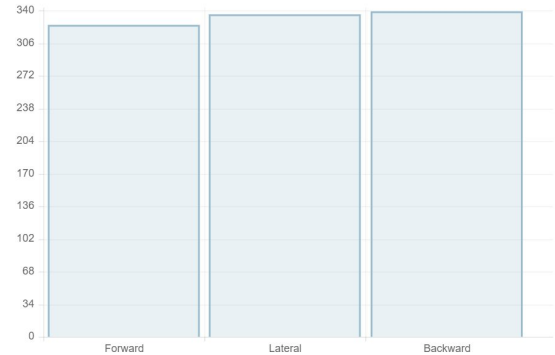
Actions Before Falling

What are people doing before they fall? Here are the stats.



Types of Falls

How are they falling? Forward? To the side?



Panic or Flame?

TECHNICAL ACHIEVEMENTS

01

Data Processing

02

Uses SQLite 3
integrated with Flask

03

User-Friendly
Visualization

04

MQTT Integrated GPS
Tracker

05

Telegram Messaging

06

GitHub Version
Control



CONSIDERATIONS



01

POWER CONSIDERATIONS

Sending GPS data only when needed instead of continuously

Sampling Rate of 20Hz following Nyquist Rate (98% of human actions capped under 10Hz)[1]



02

SECURITY

Credentials are removed when data is sent to cloud



[1] <https://www.ncbi.nlm.nih.gov/pmc/articles/PMC3859040/>

CHALLENGES

01

PAINS OF DATA COLLECTION

02

POWER DELIVERY AFFECTING IMU

03

TROUBLESHOOTING HARDWARE VS SOFTWARE



FUTURE IMPROVEMENTS

01

Collect more data for better
ML prediction

02

Continual Learning

03

Optimize Database Schema

04

GPS Tracker to run in
background of phone

05

Camera for object detection

06

Text to speech



CONCLUSION

01

SUBCOMPONENTS ARE
CHALLENGING ON THEIR
OWN

02

INTEGRATING COMPONENTS
INCREASES COMPLEXITY

03

IOT SYSTEMS CAN HAVE HUGE POSITIVE IMPACTS ON
THE SOCIETY IF IMPLEMENTED CORRECTLY





THANKS!

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